On the accuracy limits of plate theories for vibro-acoustic predictions

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Abstract

Several vibro-acoustic models for either single wall or multi-layer constructions are based on classical plate and first order shear deformation theories. The equivalent or condensed plate models employ the thin plate model to extract the dynamic mechanical properties of the multi-layer system considering only flexural and shear motions for the structure under investigation. Since these plate models do not account for the compressional or symmetric motion of the structure, both thin and thick plate theories encounter limitations for mid to high frequency predictions depending on the structures considered. In this work, analytical expressions for the frequency limit of thin and thick plate theories are derived for an elastic layer of isotropic material from the analyses of wavenumbers and admittances. Additionally, refined expressions for coincidence and critical frequencies are presented. Validation of these frequency limits are made by comparing the transmission loss (TL) obtained from both plate theories with the TL computed through the theory of elasticity for a range of thin/thick and soft/stiff materials.

Keywords: Wavenumbers, Thin plate theory, Thick plate theory, Elasticity theory, Coincidence frequency, Critical frequency

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NOMENCLATURE

\( h \) \hspace{1cm} \text{Thickness} \hspace{1cm} \theta \hspace{1cm} \text{Incident angle}

\( k_0 \) \hspace{1cm} \text{Wavenumber in the air} \hspace{1cm} k_t \hspace{1cm} \text{Transverse wavenumber}

\( k_p \) \hspace{1cm} \text{Natural propagating wavenumber} \hspace{1cm} k_b \hspace{1cm} \text{Bending wavenumber}

\( k_s \) \hspace{1cm} \text{Corrected shear wavenumber} \hspace{1cm} k_m \hspace{1cm} \text{Membrane wavenumber}

\( \delta_t \) \hspace{1cm} \text{Longitudinal wavenumber} \hspace{1cm} \delta_p \hspace{1cm} \text{Shear wavenumber}

\( \omega \) \hspace{1cm} \text{Circular frequency} \hspace{1cm} f \hspace{1cm} \text{Frequency}

\( f_{\text{cut-on}} \) \hspace{1cm} \text{Frequency limit of thin plate theory} \hspace{1cm} f_{\text{comp}} \hspace{1cm} \text{Compressional frequency}

\( f_{\text{thin/thick}} \) \hspace{1cm} \text{Coincidence frequency of a thin plate} \hspace{1cm} f_{\text{coinc/thin}} \hspace{1cm} \text{Coincidence frequency of a thin plate}

\( f_{\text{cr/thick}} \) \hspace{1cm} \text{Critical frequency of a thick plate} \hspace{1cm} f_{\text{cr/thin}} \hspace{1cm} \text{Critical frequency of a thin plate}

\( f_{\text{plate/solid}} \) \hspace{1cm} \text{Frequency limit of plate theories for diffuse field} \hspace{1cm} f_{\text{plate/solid}}/\text{full} \hspace{1cm} \text{Frequency limit of plate theories for diffuse field}

\( v^P \) \hspace{1cm} \text{State vector of a plate} \hspace{1cm} V^{ES} \hspace{1cm} \text{State vector of an elastic layer}

\( p \) \hspace{1cm} \text{Pressure at a point} \hspace{1cm} \alpha \hspace{1cm} \text{Transverse velocity at a point}

\( v \) \hspace{1cm} \text{Normal velocity at a point} \hspace{1cm} \sigma_{xx} \hspace{1cm} \text{Normal stress at a point}

\( \sigma_{xz} \) \hspace{1cm} \text{Shear stress at a point} \hspace{1cm} [T^{P}] \hspace{1cm} \text{Transfer matrix of a plate}

\( \rho \) \hspace{1cm} \text{Volume density of elastic layer} \hspace{1cm} m_s \hspace{1cm} \text{Mass density per unit area}

\( D \) \hspace{1cm} \text{Bending stiffness} \hspace{1cm} \rho_0 \hspace{1cm} \text{Volume density of air}

\( K \) \hspace{1cm} \text{Compressional modulus} \hspace{1cm} E \hspace{1cm} \text{Young’s modulus}

\( \nu \) \hspace{1cm} \text{Poisson’s ratio} \hspace{1cm} \eta \hspace{1cm} \text{Loss factor}

\( G^* \) \hspace{1cm} \text{Corrected shear modulus} \hspace{1cm} \kappa \hspace{1cm} \text{Shear correction factor}

\( I_z \) \hspace{1cm} \text{Mass moment of inertia} \hspace{1cm} \lambda, \mu \hspace{1cm} \text{Lamé coefficients}

\( \tau \) \hspace{1cm} \text{Transmission factor} \hspace{1cm} \rho_{\text{plate/solid}} \hspace{1cm} \text{Anti-symmetric impedance of a plate}

\( Z_s \) \hspace{1cm} \text{Symmetric impedance} \hspace{1cm} Z_a \hspace{1cm} \text{Anti-symmetric impedance}

\( Y_s \) \hspace{1cm} \text{Symmetric admittance} \hspace{1cm} Y_a \hspace{1cm} \text{Anti-symmetric admittance}

\( \bar{Y}_s \) \hspace{1cm} \text{Approximated symmetric admittance} \hspace{1cm} Z_0 \hspace{1cm} \text{Characteristic impedance of air}

\( C_k \) \hspace{1cm} \text{Ratio between bending and shear wavenumbers} \hspace{1cm} C_y \hspace{1cm} \text{Minimum value of ratio between anti-symmetric and symmetric admittances}

\( \epsilon \) \hspace{1cm} \text{Error percentage} \hspace{1cm} \lambda_0 \hspace{1cm} \text{Longitudinal wavelength}

1. Introduction

When studying the sound insulation of a wall, the main acoustic indicator is the transmission loss (TL) which is controlled by the combination of several fundamental vibrating modes of the wall. For example, a typical sound transmission problem encountered in building applications is presented schematically in Fig. 1 along with its vibrating modes as the acoustic energy transmitted through the wall depends on its vibro-acoustic behaviour. Although the wall vibrates in a complex manner for the given acoustic excitation, this complex motion can be obtained by superposing the fundamental
Complex motion Fundamental motions
Bending Shear Compressional

Figure 1: Schematic representation of vibrating motion of a single wall subjected to acoustic excitation.

motions (bending, shear and compressional/dilatational motions). Generally, looking at the TL characteristics of a single wall as a function of frequency, three regions can be identified which are controlled by the mass, damping and stiffness of the wall respectively. The mass and stiffness control zones are separated by a critical region where strong reduction of transmission loss is observed. This critical zone is characterized by its frequency which is called the critical frequency. Various vibro-acoustic models of varying complexity have been developed to predict the sound insulation properties of plate structures, especially with regard to noise attenuation problems. An early model was developed by Cremer [1] which was applied to the computation of the TL across infinite, thin walls. Related work approaching the same problem of computing the acoustic insulation indicators of a thin wall are presented in [2–6]. In Cremer’s model, it is assumed that the motion of the plate is described only by the bending wave equation, which is based on the classical plate theory [7].

Davy [8] argues that Cremer’s model can only be used below the critical frequency since most of the approximations are not valid within and above the critical region. Improving on Cremer’s theory, Heckl and Donner [9] developed a model based on the first order shear deformation theory (FSDT) [10–12] which could be applied to thicker walls to compute sound TL. In this model, motion due the transverse shear is also included along with the flexural motion of the plate. The corrected TL expression accounting for shear deformation of the plate can be found in [13]. Heckl and Donner [9] point out that their model is valid only at frequencies well below the first dilatational or compressional frequency of the plate. This is due to the fact that the FSDT does not account for the thickness stretch motion of the plate as it assumes constant velocity at all points through the thickness direction. Consequently, the symmetric motion of the plate is not taken into account.
in zero, first and higher order plate theories. This may lead to deviations between the predictions and the actual motion of the plate at higher frequencies, especially when the material is soft. In the work published by Ljunggren [13, 14], the general expression to compute the TL of an infinite wall with arbitrary uniform thickness is given, accounting for both antisymmetric and symmetric motions of the plate.

In recent years, instead of single wall structures, multi-layered structures have been used widely for better sound comfort and noise attenuation. These structures provide the designers with more choices for tuning the vibro-acoustic performance leading to better sound insulation characteristics. Advanced composite structures are one example of multi-layer systems that are progressively used in different fields such as the space, energy and aeronautical industries. In transport and construction industries, sandwich structures are widely used as they provide high stiffness with significantly low weight. In most cases, two face sheets are bonded with a viscoelastic layer to improve the overall damping response of the structure. There exist a large number of theoretical models dedicated to the analysis of the behaviour of multi-layer structures. According to Carrera [15, 16], these models can be classified into three major categories as: 1) Equivalent Single Layer (ESL) models, 2) Layer Wise (LW) models and 3) Hybrid or Zig-Zag models. ESL models describe the dynamics of the multi-layer plate in terms of the displacement field of an equivalent layer. It is noted that, due to this kind of displacement description, the number of layers present in the system do not influence the displacement functions which gives great flexibility in using shear deformation theories of order one [10–12] and higher [17–20]. Layer Wise (LW) models describe the displacement field in each layer [21–28]; as a consequence, this type of model requires higher computational effort as the number of unknowns increases with the number of layers present in the structure. Hybrid or Zig-Zag models make use of advantages from the previous two categories. Although the displacement field is defined in each layer (similar to the LW models), the interface continuity conditions between two adjacent layers results in a lower number of unknown functions (as in ESL models) which do not depend on the number of layers present in the structure. The reader may refer to [29–34] which use this family of models to describe the dynamic response of multi-layer systems.

Since industrial multi-layer structures are manufactured with a diversity of materials, they naturally increase the computational burden for detailed finite element modelling and it is therefore of interest to condense the behaviour of the multi-layer system into a single layer. A simplified equivalent thin plate model was developed in [35–37] for sandwich structures with a viscoelastic core. Guyader and Cacciolati [38] have developed an equivalent
thin plate model for the multi-layer structure of isotropic layers. Following a similar path, Marchetti et al. [39] have recently developed an equivalent thin plate model for laminated structures of orthotropic layers. The aim of the equivalent plate models is to find the frequency dependent mechanical parameters of the equivalent thin plate that incorporates the bending and shear motions of the multi-layer structures. Since plate theories do not account for the dilatational or compressional motion of the structure, finding a frequency domain of validity is necessary to safely use these equivalent plate models.

The reader may note that the words ‘frequency limit’ of a theory refer here to the frequency up to which the theory can be applied within pre-defined accuracy intervals for computing the desired acoustic indicators. Although in structural mechanics and dynamics, thin and thick plates are distinguished based on the thickness to lateral dimensions ratio [40, 41], such rules may not be sufficient for vibro-acoustic calculations as they depend on the material properties of the plate as well. Additionally, although plate theories (both for thin and thick plates) are commonly employed in computing the acoustic indicators of infinite and finite walls, there is currently no clear-cut frequency limit to restrict the applicability of these theories. Qualitative and approximate frequency limits are given in the literature but it is often a tedious task to find an analytical expression for applicability limits.

In this work, we derive for the first time analytical expressions for the applicability limits in the spectral domain for thin and thick plate theories. Through analysis of the propagating wavenumbers and admittances of the investigated panels, we quantify the expected accuracy of each theory. The paper is organized as follows: Sec. 2 describes the theories behind propagating wavenumbers inside thin, thick plates and elastic solids. The theory of elastic solids is treated as a reference since it describes the complete motion of an infinite layer [42]. In Sec. 3, expressions for the limits of applicability of thin plate theories are discussed by comparing propagating wavenumbers of thin and thick plate theories. Additionally, refined expressions for the coincidence and critical frequencies are also presented. In Sec. 4, an expression for the frequency limit of applicability of plate theories is derived in all generality by comparing the order of magnitudes of both symmetric and anti-symmetric admittances of the plate. In Sec. 5, analytical expressions for the frequency limits of different plate theories are presented along with sound transmission loss computations for classical industrial materials for validation purposes.
2. Vibro-acoustic models for an elastic isotropic layer

We start by giving the theoretical background for some commonly used theories such as the Love-Kirchoff \cite{7, 43} or the Reissner-Mindlin \cite{10–12} theory used to describe the vibro-acoustic behaviour of isotropic, single wall structures. In subsequent sections, these theories are compared and their limitations are discussed.

2.1. Wave propagation in an elastic isotropic plate

Let us consider an infinitely extended elastic medium with thickness $h$ as shown in Fig. 2. An oblique wave is assumed to be impinging upon one of the surfaces of the elastic medium with an incident angle $\theta$. For the sake of simplicity, the incident plane wave is assumed to be in the $x-z$ plane. Depending on the material properties of the elastic layer, various types of wave propagation are possible. The wave propagation in the $x-z$ plane will have wave vector components along the $x$ and $z$ axes for each wave. The incident wave in free air is exciting waves inside the elastic medium; continuity across the interface demands that the transverse or $x$ component of the wave vector, $k_t$, for waves propagating in the plate and in air are equal. We have

$$k_t = k_0 \sin \theta = \frac{\omega}{c_0} \sin \theta, \tag{1}$$

where $k_0$ is the wavenumber in free air, $\omega = 2\pi f$ is the circular frequency of the incident wave and $c_0$ is the speed of sound in air. If the acoustic field in the elastic layer (Fig. 2) is described by the state vector $V^P = \{p, v\}^T$ (where the superscript $P$ denotes plate, $p$ is the acoustic pressure and $v$, the particle velocity normal to the interface), then the general form of the transfer matrix for plate theories discussed can be expressed by the following equation:

$$V^P_M = [T^P] V^P_{M'}, \tag{2}$$
Here, $M$ and $M'$ are points on the left and right hand side on the surface of the elastic medium, respectively and $Z_P$ is the anti-symmetric mechanical impedance of the plate, that is, the ratio of the differential complex sound pressure across the plate to the complex plate velocity; it is expressed as below based on the theory adopted, that is,

$$Z_P = \begin{cases} Z_{\text{thin}} = j\omega m_s \left( 1 - \frac{Dk_t^4}{\omega^2 m_s} \right) \\ Z_{\text{thick}} = \frac{k_t^4 D - m_s \omega^2 + \left( I_z m_s \omega^2 - k_t^2 D m_s \right) \omega^2 - k_t^2 I_z \omega^2}{j\omega \left( \frac{k_t^2 D - I_z \omega^2}{G^* h} + 1 \right)} \end{cases} , \quad (3)$$

where Love-Kirchoff theory applies for thin plates and Reissner-Mindlin theory for thick plates. Here, $m_s$ is the mass density per unit area,

$$D = \frac{E(1 + j\eta)h^3}{12(1 - \nu^2)}$$

is the bending stiffness, $E$ is the Young’s modulus, $j = \sqrt{-1}$, $\eta$ is the loss/damping factor, $\nu$ is the Poisson’s ratio, $G^* = \kappa G$ with $G$, the shear modulus of the plate and $\kappa$, the shear correction factor accounting for the transverse shear distribution. Furthermore,

$$I_z = \frac{\rho h^3}{12}$$

is the mass moment of inertia of the plate and $\rho = m_s/h$ is the volume density of the plate material. Detailed derivations of the mechanical impedances given in Eq. (3) can, for example, be found in the book by Cremer and Heckl [44].

When using the thick plate theory, the shear correction factor, $\kappa$, is substituted with different values/expressions by different authors. For example, Reissner [11] and Mindlin [10] used the values 5/6 and $\pi^2/12$, respectively, for the shear correction factor, whereas Heckl and Donner [9] used the following expression given by Maggrab [45],

$$\kappa = \left( \frac{0.87 + 1.12\nu}{1 + \nu} \right)^2$$

which is a function of the Poisson’s ratio of the plate. In this article, the value of $\kappa$ is taken as 5/6.
2.1.1. Dispersion relations

Given the mechanical impedances of the structure, dispersion relations are often obtained by setting the impedance to zero. In other words, dispersion relations are used to understand the wave propagation in the structure under natural or free vibration conditions.

For Love-Kirchhoff plates (or thin plates), by setting the mechanical impedance equal to zero, it can be observed that only one type of wave propagation is possible, that is,

\[ Z_{\text{thin}} = 0 \Rightarrow k_p^4 D - m_s \omega^2 = 0 \Rightarrow k_p = k_b = \sqrt{\frac{m_s}{D}}, \quad (4) \]

where \( k_b \) corresponds to the bending wavenumber and \( k_p \) is the natural propagating wavenumber of the plate.

For Reissner-Mindlin plates (or thick plates), the dispersion relation is obtained as

\[ Z_{\text{thick}} = 0 \Rightarrow k_p^4 D - m_s \omega^2 + \left( \frac{I_z m_s}{G^* h} \omega^2 - k_p^2 D m_s \right) \omega^2 - k_b^2 I_z \omega^2 = 0. \quad (5) \]

There are four possible solutions for the above quartic equation, that is,

\[ k_p = \pm \sqrt{\frac{m_s \omega^2}{2G^* h}} \pm \sqrt{\frac{m_s \omega^2}{2D}} \pm \sqrt{\frac{m_s \omega^2}{2G^* h} - \frac{I_z \omega^2}{2D}}. \quad (6) \]

Out of the four solutions, two correspond to outgoing waves, that is, the real part of the wavenumber is positive; these are

\[ k_p = k_{RM_{1,2}} = \sqrt{\frac{m_s \omega^2}{2G^* h}} + \sqrt{\frac{m_s \omega^2}{2D}} \pm \sqrt{\frac{m_s \omega^2}{2G^* h} - \frac{I_z \omega^2}{2D}}. \quad (7) \]

It is observed from the above equation that the propagating wavenumber \( (k_{RM_i}) \) has different asymptotic behaviour with respect to low and high frequencies as shown in Fig. 3, here for the example of a 50 mm plasterboard with mechanical properties listed in Table 1. One finds in particular:

- At low frequency (or \( \omega \to 0 \)), we have

\[ \frac{m_s}{D} \gg \left( \frac{m_s}{2G^* h} - \frac{I_z}{2D} \right)^2 \omega^2 \]

which results in \( k_{RM_1} \) tending to \( k_b \).
Figure 3: Propagating wavenumbers of a Reissner-Mindlin plate (50 mm plasterboard with mechanical properties mentioned in Table 1) and its asymptotic behaviours. It is observed that the main natural propagating wavenumber $k_{RM1}$ is approaching bending ($k_b$) and corrected shear wavenumbers ($k_s$) at low and high frequencies respectively.

- At high frequency (or $\omega \to +\infty$), we find
  \[
  \frac{m_s}{D} \ll \left( \frac{m_s \omega^2}{2G^* h} - \frac{I_z}{2D} \right)^2 \omega^2
  \]
  which results in $k_{RM1}$ tending to $k_s = \omega \sqrt{\frac{m_s}{G^* h}}$ with $k_s$, the corrected shear wavenumber.

- $k_{RM2}$ is evanescent until the cut-on frequency given by Eq. (9) after which it becomes propagating and reaches the membrane wavenumber $k_m = \omega \sqrt{\frac{I_z}{D}}$ at high frequency.

- $k_s$ is always greater than $k_m$ since $\frac{k_s}{k_m} = \sqrt{\frac{2}{\kappa(1-\nu)}} > 1$
Based on the above observations, Eq. (7) is rewritten in a compact form as,

$$k_{RM_{1,2}} = \sqrt{\frac{1}{2} \left[ k_x^2 + k_m^2 \pm \sqrt{4k_b^4 + (k_x^2 - k_m^2)^2} \right]}.$$  \hspace{1cm} (8)

The cut-on frequency can be obtained by considering $k_{RM_2} = 0$, that is,

$$k_x^2 + k_m^2 = \sqrt{4k_b^4 + (k_x^2 - k_m^2)^2} \Rightarrow k_b^4 = k_x^2k_m^2$$

and thus

$$f_{cut-on} = \frac{1}{2\pi} \sqrt{\frac{G^*h}{I_z}}.$$  \hspace{1cm} (9)

Further, it is observed that the high frequency asymptote given by Ghinet and Atalla [27] as

$$k_{G&\text{A}} = \omega \sqrt{\frac{4I_zm_s}{G^*hI_z + m_sD}},$$ \hspace{1cm} (10)

differs from the correct estimation of the high frequency asymptote $k_s$. It may be noted that Eq. (5) can be obtained from two of the three equilibrium equations (derived by a Newtonian approach) for thick plates [46]. For the sake of completeness, the dispersion relation resulting from third equilibrium equation [27] is presented here. The natural wavenumber from the third equilibrium equation is given by,

$$k_p = k_{RM_3} = \sqrt{\frac{2}{1 - \nu} \frac{I_z\omega^2 - G^*h}{D}} = \sqrt{\delta_s^2 - \frac{2}{1 - \nu} \frac{k_b^4}{k_x^2}},$$ \hspace{1cm} (11)

where $\delta_s = \omega \sqrt{\frac{\rho}{G}}$ is the pure shear wavenumber of the isotropic elastic layer.

Similar to $k_{RM_2}$, $k_{RM_3}$ is also evanescent until a cut-on frequency ($f_{cut-on}$) but reaches the asymptote $\delta_s$ at higher frequencies as

$$\delta_s^2 \gg \frac{2}{1 - \nu} \frac{k_b^4}{k_x^2}$$

when $\omega \to +\infty$. Fig. 3 illustrates these asymptotic behaviours of the solutions of $k_{RM}$ for a plasterboard of thickness 50 mm. Mechanical properties of the materials used in this paper can be obtained from Table 1.

The transmission loss across an infinite layer surrounded by air (defined by the equation $V_M = |T|_{2\times2}V_M'$) for an oblique incidence may be computed from the following expression:

$$TL = -10 \log_{10} \tau,$$ \hspace{1cm} (12)
Table 1: Material properties of few typical elastic isotropic layers used in this paper

<table>
<thead>
<tr>
<th>Properties</th>
<th>Aluminium</th>
<th>Plasterboard</th>
<th>Concrete</th>
<th>Soft layer</th>
</tr>
</thead>
<tbody>
<tr>
<td>ρ (kg/m³)</td>
<td>2780</td>
<td>700</td>
<td>2150</td>
<td>8</td>
</tr>
<tr>
<td>E (GPa)</td>
<td>71</td>
<td>3</td>
<td>33</td>
<td>0.00016</td>
</tr>
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<td>η</td>
<td>0.01</td>
<td>0.08</td>
<td>0.1</td>
<td>0.1</td>
</tr>
<tr>
<td>ν</td>
<td>0.3</td>
<td>0.22</td>
<td>0.23</td>
<td>0.44</td>
</tr>
</tbody>
</table>

where

\[
\tau(\theta) = 4\left| T_{11} + T_{22} - \left( \frac{T_{12} \cos \theta}{Z_0} + \frac{T_{21} Z_0}{\cos \theta} \right) \right|^2
\]

is the transmission factor, \( Z_0 = \rho_0 c_0 \) is the characteristic impedance of air and \( \rho_0 \) is the density of air. In this paper, the values for \( c_0 \) and \( \rho_0 \) are taken as 343 m.s⁻¹ and 1.2 kg.m⁻³, respectively. The reader may note that for plate theories, the transmission factor is reduced to the form

\[
\tau(\theta) = \frac{1}{1 - \left| \frac{Z_0 \cos \theta}{2Z_0} \right|^2}
\]

In case of a diffuse field excitation with minimum and maximum angle of incidences as \( \theta_{\text{min}} \) and \( \theta_{\text{max}} \), respectively, the TL is obtained computing the following integral:

\[
TL_d = -10 \log_{10} \left[ \frac{\int_{\theta_{\text{min}}}^{\theta_{\text{max}}} \tau(\theta) \sin \theta \cos \theta \, d\theta}{\int_{\theta_{\text{min}}}^{\theta_{\text{max}}} \sin \theta \cos \theta \, d\theta} \right].
\]  

(13)

TL computed based on both thin and thick plate theories for the materials given in Table 1, are analyzed in the Section 5.

It must be realized that both thin and thick plate theories neglect the compressional mode (also called the symmetric or dilatational mode) and allow only anti-symmetric modes (i.e., bending and/or shear modes), since the plate velocity is assumed to be constant through the thickness direction.

2.2. Wave propagation in elastic isotropic solids

From the principles of the theory of elasticity, it can be derived that two fundamental waves can propagate through an isotropic medium corresponding to longitudinal and shear displacement in the solid. Longitudinal \((\delta_l)\)
and shear ($\delta_s$) wave numbers are given as \[42\],

\[
\delta_l = \omega \sqrt{\frac{\rho}{\lambda + 2\mu}} = \omega \sqrt{\frac{\rho}{K}}, \quad \delta_s = \omega \sqrt{\frac{\rho}{\mu}},
\]

(14)

where $K = \lambda + 2\mu$ is the compressional modulus of the elastic solid which highly influences the symmetric motions of the layers in a solid,

\[
\lambda = \frac{E\nu}{(1 + \nu)(1 - 2\nu)}
\]

is the first Lamé coefficient and $\mu = G$ is the second Lamé coefficient.

Assuming an acoustic wave incident on the surface of the solid with angle $\theta$, the resulting wavenumbers that propagate inside the elastic solid have a $z$ component of the form,

\[
k_{lz} = \sqrt{\delta_l^2 - k_t^2}, \quad k_{sz} = \sqrt{\delta_s^2 - k_t^2}.
\]

(15)

By following Folds and Loggins \[47\], the state vector is taken as $V_{ES} = \{u, v, \sigma_{zz}, \sigma_{xz}\}$ where the superscript ES denotes elastic solid, $\sigma_{xz}$ and $u$ are the transverse components of the stress and the velocity, and $\sigma_{zz}$ and $v$ the normal components of the stress and the velocity respectively. The transfer matrix for elastic solid is then expressed as

\[
V_{M'}^{ES} = [T^{ES}]_{4 \times 4} V_{M}^{ES},
\]

(16)

where the elements of the matrix $[T^{ES}]$ are given in the Appendix A. For the computation of sound transmission loss across an infinite layer based on the solid transfer matrix, the reader may refer to the procedure given in the book by Allard and Atalla \[42\].

Based on the type of backing at point $M'$, the frequency of the first compressional mode of an elastic layer is given as

\[
f_{\text{comp}} = \frac{1}{\gamma h} \sqrt{\frac{K}{\rho}},
\]

(17)

where $\gamma$ takes on the values 2 (half wave frequency) and 4 (quarter wave frequency) for anechoic and rigid backing respectively.

Since the motion both of the anti-symmetric and compressional mode of an infinite layer of finite thickness can be expressed based on the theory of elasticity, calculations of the transfer matrix for elastic solids are considered here as reference to the analyse using plate theories. By referring to the two fundamental wavenumbers ($\delta_l$ and $\delta_s$) of the elastic isotropic solid, it can be understood that the bending wavenumber is a complex combination of these fundamental wavenumbers. It is, however, not straightforward to see this relation from the above equations for elastic isotropic solids.
3. Comparison between thin and thick plate theories

3.1. Frequency limit of thin plate theory in comparison with thick plate theory

In this section, natural propagating wavenumbers of thin and thick plate theories are used to find the frequency limit of the thin plate theory. From the Fig. 3, it can be seen that the thick plate wavenumber \( k_{RM_1} \) clearly deviates from the bending wavenumber \( k_b \) after certain frequency. It may be noted that, though there are totally three outgoing waves characterized by wavenumbers \( (k_{RM_1}, k_{RM_2}, k_{RM_3}) \), \( k_{RM_1} \) is considered for the present analysis as it is the only wavenumber that is always propagative. Additionally, since the deviation between \( k_{RM_1} \) and \( k_b \) starts well before the cut-on frequency \( f_{\text{cut-on}} \), \( k_{RM_1} \) would be appropriate to derive the frequency limit of thin plate theory. By defining \( C_k = \frac{k_b}{k_s} \), the ratio between bending and shear wavenumbers, error percentage \( (\epsilon) \) between the propagating wavenumbers of the thin and thick plate theories is expressed as

\[
\epsilon = \left(1 - \frac{1}{k_{RM_1}/k_b}\right) \times 100\%,
\]

where

\[
k_{RM_1} = \frac{1}{2} \sqrt{\frac{2 + \kappa(1 - \nu)}{C_k^2} + \frac{(2 - \kappa(1 - \nu))^2}{C_k^2}}.
\]

The thin plate theory will be valid while \( k_s \) is negligible compared to \( k_b \) \((k_b \gg k_s)\). The value for \( C_k \) can be chosen such that \( \epsilon \) is below an accepted error percentage and the frequency range of validity for thin isotropic plate can be expressed as given by Eq. (20).

\[
f_{\text{thin/thick}} \geq C_k k_s \Rightarrow f \leq f_{\text{thin/thick}} = \frac{G^* h}{2\pi C_k^2} \sqrt{\frac{1}{m_s D}} = \frac{\kappa}{4\pi h C_k^2} \sqrt{\frac{12E}{\rho (1 + \nu)}},
\]

where \( f_{\text{thin/thick}} \) is the frequency limit of the ‘thin’ plate theory by keeping the ‘thick’ plate theory as reference. For instance, choosing \( C_k = 4 \) for typical isotropic layer corresponds to an error percentage \( (\epsilon) \) around 2% between \( k_{RM_1} \) and \( k_b \).

3.2. Coincidence and critical frequencies of thick plate

As discussed in the earlier sections, thin plate theory allows only bending waves to propagate in the elastic plate and shear wave propagation is included by thick plate theory to correctly capture the anti-symmetric motion of the plate. Due to this additional anti-symmetric motion in the plate, the
coincidence and critical frequency expressions obtained from thin plate theory need to be rewritten with terms corresponding to shear and rotational inertia.

The coincidence frequency between a plate and an acoustic wave incident on the plate at an angle $\theta$ is defined as the frequency at which the transverse component of the incident wavenumber is equal to the natural propagating wavenumber of the plate. In the case of thin plates, the natural propagating wavenumber is the bending wavenumber and the coincidence frequency is expressed as,

$$k_b = k_0 \sin \theta \implies f_\text{coinc}_{\text{thin}} = \frac{1}{2\pi} \left( \frac{c_0}{\sin \theta} \right)^2 \sqrt{\frac{m_s}{D}}.$$  \hfill (21)

For thick plates, as the natural propagating wavenumber is given by $k_{RM1}$, the coincidence frequency is expressed as,

$$k_{RM1} = k_0 \sin \theta \implies f_\text{coinc}_{\text{thick}} = \frac{(c_0/ \sin \theta)^2}{2\pi \sqrt{\left( \frac{D}{m_s} - \frac{c_0^2 I_z}{\sin^2 \theta m_s} \left( 1 - \frac{c_0^2 m_s}{\sin^2 \theta G^* h} \right) \right)}}.$$ \hfill (22)

In case of diffuse field excitation, the elastic layer is subjected to all coincidence frequencies corresponding to $\theta = [0, \pi/2]$ and the lowest coincidence frequency is called the critical frequency. In other words, it is the frequency at which the speed of sound is equal to the speed of natural propagating waves of the plate. This can be computed by letting $\sin \theta = 1$ in the coincidence frequency expression. The critical frequency obtained from thin plate theory is given by $k_b = k_0$, that is,

$$f_\text{cri}_{\text{thin}} = \frac{c_0^2}{2\pi} \sqrt{\frac{m_s}{D}}.$$ \hfill (23)

From the Eq. (22), the critical frequency for thick plate is obtained from $k_{RM1} = k_0$, that is,

$$f_\text{cri}_{\text{thick}} = \frac{c_0^2}{2\pi \sqrt{\left( \frac{D}{m_s} - \frac{c_0^2 I_z}{m_s} \left( 1 - \frac{c_0^2 m_s}{G^* h} \right) \right)}}.$$ \hfill (24)

It may be noted that the Eqs. (22) and (24) tend to coincidence and critical frequencies obtained from thin plate theory as $I_z \to 0$ and $G^* \to \infty$. As an illustration, for 12.5 mm plasterboard, the coincidence frequencies computed
Figure 4: Transmission loss for the infinitely extent plasterboard of thickness 12.5 mm (properties are mentioned in Table 1) under plane wave excitation with $\theta = 60^\circ$ with coincidence frequencies computed from thin & thick theories and it can be observed that the estimation of coincidence frequency from thick plate theory is in good agreement with theory of elasticity computation.

from both plate theories are indicated in the Fig. 4. It is observed from the Fig. 4 that the coincidence frequency computed from Eq. (22) is in good agreement with elasticity theory. Therefore, it is worth noting that Eqs. (21) and (23) are indeed limited to thin plates only, where the transition from thin to thick plates is given by the frequency $f_{\text{thin/thick}}$ in Eq. (20).

4. Frequency limit of plate theories in comparison with theory of elasticity

When the thickness of the layer is small compared to the lateral dimension and the longitudinal wavelength ($\lambda_l = 2\pi/\delta_l$) is large compared to thickness, a plate theory, controlled by the anti-symmetric motion, is generally considered. On the contrary, when the thickness of the plate is of the order
of magnitude of longitudinal wavelength, due to the variation in velocity through the thickness of the layer, both symmetric and anti-symmetric motions contribute for the resulting motion of the plate after a certain frequency (Fig. 5). This implies that plate theories might not be able to predict the correct vibro-acoustic behaviour of the elastic layer after this frequency as they assume only anti-symmetric motions in the plate. Therefore, finding this frequency limit of plate theories is necessary and in this section, based on the symmetric and anti-symmetric motions of the plate, the analytical expression of the frequency limit of plate theories is derived.

Contributions of symmetric and anti-symmetric motions of an isotropic layer can be quantified by the impedances or admittances, by following Dym and Lang [48]. Impedances of symmetric and anti-symmetric motions are defined as follows [48],

\[ Z_s = \frac{2pM + pM'}{v_M - v_{M'}} \quad \text{(25)} \]

\[ Z_a = \frac{2pM - pM'}{v_M + v_{M'}} \quad \text{(26)} \]

where \( Z_s \) and \( Z_a \) are symmetric, anti-symmetric impedances of the layer respectively and \( p \) and \( v \) are pressure and velocity respectively. It may be noted that though Dym and Lang [48] assumed \( p_{M'} = 0 \) in their analysis, later, they have corrected the definitions of impedances with non-zero pressure values [49].

The above equations are rewritten to obtain the transfer matrix relations as follows,

\[ \begin{pmatrix} p \\ v \end{pmatrix}_M = \frac{1}{Y_a - Y_s} \begin{bmatrix} Y_a + Y_s & 1 \\ 4Y_aY_s & Y_a + Y_s \end{bmatrix} \begin{pmatrix} p \\ v \end{pmatrix}_{M'} . \quad \text{(27)} \]

Here, \( Y_s = 1/Z_s \) and \( Y_a = 1/Z_a \) are the symmetric and anti-symmetric admittances of the layer respectively. It can be checked that, when the anti-symmetric admittance is larger than the symmetric admittance (or \( Y_a \gg Y_s \)), the transfer matrix in Eq. (27) reduces to the transfer matrix of the plate.
given by Eq. (2). Thus the ratio between $Y_a$ and $Y_s$ could be a good criterion to obtain the frequency limit of plate theories. Comparing the longitudinal wavelength ($\lambda_l$) to the thickness of the plate seems less accurate as it does not compare the symmetric motion to the anti-symmetric motion.

Since the symmetric motion is controlled by the longitudinal wave of the layer, the transfer matrix from Eq. (16) is deduced at normal incidence as

$$\begin{pmatrix} p \\ v \end{pmatrix}_M = \begin{bmatrix} \cos h \delta_l & j \omega \rho / \delta_l \sin h \delta_l \\ j \delta_l / \omega \rho \sin h \delta_l & \cos h \delta_l \end{bmatrix} \begin{pmatrix} p \\ v \end{pmatrix}_{M'}.$$  \hspace{1cm} (28)

By equating the above equation with Eq. (27), the symmetric admittance is obtained as

$$Y_s = \frac{h \delta_l (\cos h \delta_l - 1)}{2 j m_s \omega \sin h \delta_l} = -\frac{h \delta_l}{2 j m_s \omega} \tan \frac{h \delta_l}{2}.$$ \hspace{1cm} (29)

Approximating the tangent function by a Taylor series expansion (up to first order), the symmetric admittance can be written as,

$$\tan \frac{h \delta_l}{2} \approx \frac{h \delta_l}{2} \implies Y_s \approx \tilde{Y}_s = \frac{(h \delta_l/2)^2}{j \omega m_s} = \frac{j \omega h}{4K}.$$ \hspace{1cm} (30)

Since the anti-symmetric motion is controlled by the transverse wavenumber of the incident wave and plate theories capture this type of motion, anti-symmetric admittance is computed from plate theories as given by Eq. (3).

The minimum value of the absolute ratio between the anti-symmetric and symmetric admittance, denoted by $C_y$, is used to find the frequency limit of plate theories. Expressing the anti-symmetric admittance ($Y_a$) from thin plate theory and the symmetric admittance ($\tilde{Y}_s$) from Eq. (30), the frequency limit of plate theories is expressed as

$$\left| \frac{Y_a}{Y_s} \right| \geq C_y \implies f \leq f_{\text{plate/solid}} = \frac{c_0^2}{2\pi \sin^2 \theta} \sqrt{\frac{m_s}{2D} \pm \sqrt{\left(\frac{m_s}{2D}\right)^2 + \frac{4K}{2D} \sin^4 \theta}}.$$ \hspace{1cm} (31)

The above expression is valid for oblique incidence whereas in case of diffuse field excitation, the following expression may be used to compute the frequency limit of plate theories.

$$\left| \frac{Y_a}{Y_s} \right| \geq C_y \implies f \leq f_{\text{plate/solid}} = \frac{c_0^2}{2\pi} \sqrt{\frac{m_s}{2D} \pm \sqrt{\left(\frac{m_s}{2D}\right)^2 + \frac{4K}{2D} \frac{1}{hC_y D c_0^4}}}.$$ \hspace{1cm} (32)
The above frequency limits are computed by keeping the loss factor ($\eta$) to be zero. The subscript ‘plate/solid’ in the above equations means that the frequency limit is for ‘plate’ theories in general (as even higher order plate theories also do not account for symmetric motion) by keeping as a reference the theory of ‘elastic solids’. Further, the sub-subscripts ‘oi’ and ‘df’ correspond to ‘oblique incidence’ and ‘diffuse field’ respectively. It may be observed that the relation $\frac{Y_a}{Y_s} \geq C_y$ yields four positive roots for the frequency. Out of these four roots, only the minimum of pure real roots is considered for $f_{\text{plate/solid}_{oi}}$ and $f_{\text{plate/solid}_{df}}$. It may also be noted that the expression for $f_{\text{plate/solid}_{df}}$ can be modified in two ways. First, by including higher order terms for the tangent function to get $\tilde{Y}_s$. Second, by using the anti-symmetric mechanical admittance from thick plate theory. Though these two ways might improve the frequency limit, the final expression for $f_{\text{plate/solid}_{df}}$ would become more complex. Further, as discussed in the next section, the frequency limits given by Eqs. (31) and (32) are sufficient enough for typical single layer walls used in industry. A concrete layer of 140 mm is taken to illustrate the nature of the symmetric and anti-symmetric admittances of the elastic layer and presented in the Fig. 6.

From the Fig. 6, it can be seen that the anti-symmetric admittance is larger compared to the symmetric admittance at low frequency range. The symmetric admittance is seen to become of the same order of magnitude or larger compared to the anti-symmetric impedance at around 2000 Hz. By letting the factor $C_y$ to be 10, the frequency limit of plate theories is computed from Eq. (32). This means that the anti-symmetric admittance is one order of magnitude larger than the symmetric admittance and from this frequency onwards use of plate theories is not recommended to compute the acoustic indicators. Therefore, it is advisable to adopt the theory of elasticity for computations after this frequency limit.
5. Numerical examples

In this section, transmission loss (TL) of different material layers (with properties listed in Table 1) are presented to illustrate the frequency limits obtained in sections 3 and 4. Both, oblique plane wave incidence of 60° and diffuse fields, are used to compute TL. Since \( f_{\text{plate/solid} \downarrow} \) is the minimum of all the possible coincidence frequencies obtained from \( f_{\text{plate/solid} \uparrow} \), in this section, \( f_{\text{plate/solid} \downarrow} \) is indicated as the limit of plate theory. Though elasticity theory is considered as reference to analyse the plate theories, additional validation from finite element method (FEM) is also presented in some of the TL plots in this section.

FEM simulations are computed using Comsol Multiphysics© software. The acoustical variables (pressure, velocity fields...) are computed in the coupled system (PML-air-material-air-PML) using the “Comsol Pressure Acoustics” interface (Helmholtz equation) for air and “Structural Mechanics branch” for the material (elastic material in “Solid Mechanic”). The interface between air and the material is modelized using “fluid-structure interface”. The dimensions of each material are 60 cm × 60 cm (the thickness is the real thick-
ness) and periodic lateral conditions are chosen. The domain is adjusted (in particular the dimensions of the air domains) and meshed with respect to a 10 elements per wavelength (of the incident plane wave excitation) criterion based on the maximal frequency. For example, at 125 Hz, the number of resolved degrees of freedom is 444675, the complete mesh consists of 29889 domain elements, 8802 boundary elements and 812 edge elements.

In Figs. 7 and 8, TL computed from different theories (discussed in the section 2) are presented for comparison along with frequency limits expressed in sections 3 and 4. It is observed from these plots that, for material like aluminium (with typical value of thickness used in industries), the thin plate theory would be sufficient to model the vibro-acoustic behaviours as both $f_{\text{thin/thick}}$ and $f_{\text{plate/solid}}$ are spotted near the maximum audible frequency.

Figure 7: Transmission loss for an aluminium layer of thickness 5 mm (properties mentioned in Table 1) under plane wave excitation with $\theta = 60^\circ$. It is seen that thin plate theory is adequate to compute the vibro-acoustic indicators as both limiting frequencies ($f_{\text{thin/thick}}$ & $f_{\text{plate/solid}}$) are in the high frequencies.
Figure 8: Transmission loss for an aluminium layer of thickness 5 mm (properties mentioned in Table 1) under diffuse field excitation. It is seen that thin plate theory is adequate to compute the vibro-acoustic indicators as both limiting frequencies \( f_{\text{thin/thick}} \) and \( f_{\text{plate/solid}} \) are in the high frequencies.

For the plasterboard of 12.5 mm, it is seen from the Figs. 9 and 10 that TL computed from thin plate theory is beginning to deviate from the elasticity theory computation whereas thick plate theory is still in good agreement with the elasticity theory until the limiting frequency \( f_{\text{plate/solid}} \). This explains the need to include the effect of shear into the anti-symmetric motion via thick plate theory. Therefore, for these kind of materials, thick plate theory would be appropriate to compute the acoustic indicators.
Figure 9: Transmission loss for a plasterboard layer of thickness 12.5 mm (properties mentioned in Table 1) under plane wave excitation with $\theta = 60^\circ$. Deviations of thin and thick plate theories from the elastic solid theory (or FEM) are observed after $f_{\text{thin/thick}}$ and $f_{\text{plate/solid}}$ respectively.

Figure 10: Transmission loss for a plasterboard layer of thickness 12.5 mm (properties mentioned in Table 1) under diffuse field excitation. Deviations of thin and thick plate theories from the elastic solid theory are observed after $f_{\text{thin/thick}}$ and $f_{\text{plate/solid}}$ respectively.
In case of a concrete layer with 140 mm thickness, it is noted from Figs. 11 and 12 that a similar trend is observed as for the plasterboard, that is, thin and thick plate theories are starting to deviate from the elasticity theory computation at frequencies above $f_{\text{thin/thick}}$ and $f_{\text{plate/solid,tf}}$, respectively. One might also observe two notable points from the TL plots of concrete and plasterboard. First, the coincidence frequency occurs after the limit frequency of thin plate ($f_{\text{thin/thick}}$) in plasterboard whereas it can be spotted before $f_{\text{thin/thick}}$ in concrete. This implies that even for thicker material the thin plate theory might be still valid after the coincidence frequency. The second notable point is that the symmetric motion (or compressional motion) effect clearly appears in concrete. In Fig. 12, the second minima in the TL computed from the theory of elasticity corresponds to the compressional frequency ($f_{\text{comp}} \approx 15 \text{ kHz}$) given by Eq. (17). Therefore, it is inferred that the compressional mode can still be neglected for plasterboard whereas it has to be taken into account for the concrete layer and this is possible via employing the theory of elasticity. The same is observed from the TL plots (Figs. 13 & 14) of soft layer with 20 mm thickness. It can be seen that TL of soft layer is greatly influenced by the symmetric motion after the frequency limit $f_{\text{plate/solid,tf}}$.

Figure 12: Transmission loss for a concrete layer of thickness 140 mm (properties mentioned in Table 1) under diffuse field excitation. Deviations of thin and thick plate theories from the elastic solid theory start to appear after $f_{\text{thin/thick}}$ and $f_{\text{plate/solid,tf}}$ respectively.
Figure 11: Transmission loss for a concrete layer of thickness 140 mm (properties mentioned in Table 1) under plane wave excitation with $\theta = 60^\circ$. Deviations of thin and thick plate theories from the elastic solid theory (or FEM) start to appear after $f_{\text{thin/thick}}$ and $f_{\text{plate/solid}}$, respectively.

Figure 13: Transmission loss for a soft layer of thickness 20 mm (properties mentioned in Table 1) under plane wave excitation with $\theta = 60^\circ$. Deviations of plate theories from the elastic solid theory (or FEM) start to appear after $f_{\text{plate/solid}}$. 
Figure 14: Transmission loss for a soft layer of thickness 20 mm (properties mentioned in Table 1) under diffuse field excitation. Deviations of plate theories from the elastic solid theory start to appear after $f_{\text{plate/solid}}$. 

One can also observe from Eq. (20) that, for different materials of infinitely extending layers with same thickness, the frequency limit $f_{\text{thin/thick}}$ would result in different values despite thicknesses being the same. Therefore, it can be inferred that the use of thin plate theory requires proper combination of thickness and material properties (as given by Eq. (20)) rather than comparing the thickness to the lateral dimensions. Similar argument holds for $f_{\text{plate/solid}}$ as well. In the previous TL plots, the choice of the values of $C_k = 4$ and $C_y = 10$ are further confirmed by the TL variation of plate theories from the elasticity theory and the TL difference between the elasticity theory and plate theories are observed to be below 1 dB at the frequency limits. Of course, one can conveniently choose the appropriate value of $C_k$ and $C_y$ based on the tolerance accepted for the particular acoustic design.

5.1. Further observation

In the case of finite sized plates, generally, the acoustic indicators computed from the infinitely extent layer theories would yield some discrepancies in the low to mid frequencies compared with experimental tests. Therefore, there are some works in the literature [5, 50] which focus on correcting the
acoustic indicators by introducing correction factors that account for geo-
metrical size effect.

Figure 15: Transmission loss, computed from spatial windowing method by Rhazi and Atalla [50], across a finite size (3 m × 4 m) plasterboard of thickness 12.5 mm (properties are mentioned in Table 1) under diffuse field excitation. It is observed that limiting frequencies computed for infinite plate are still valid for the finite plates as the size correction effects minimal near the critical frequency of the plate.

Since the radiation efficiency (which accounts for size correction in sound transmission problems) is reaching unity near the critical frequency of the plate [44], the effects due to finite size is mainly visible at low frequencies below the critical frequency. Since the frequency limits \( f_{\text{thin/thick}} \) and \( f_{\text{plate/solid}} \) of typical industrial materials fall near and/or after the critical frequency, these limiting expressions obtained from infinite plate theories are applicable to the finite size plate as well. For example, this can be observed from the transmission loss computed from the finite size correction model by Rhazi and Atalla [50] for the plasterboard of 12.5 mm thickness under diffuse field excitation in Fig 15.

6. Concluding remarks

The assumptions used in thin and thick plate theories limit their applica-
bility in commonly used industrial materials after a certain frequency. Thin
plate theory attains the limitation since it does not account for the shear effect in the anti-symmetric motion of the plate whereas this is considered in thick plate theories. Nevertheless, both types of plate theories are approximations since they neglect symmetric motion of the panel in their theoretical formulation. By analysing the wavenumbers and admittances of the investigated structures, two frequency limits were presented in this manuscript: 1) from the wave propagation analysis of the thick plate model, based on the Reissner-Mindlin plate hypothesis, the analytical expression for the limiting frequency of the thin plate model is derived, while 2) from comparing the symmetric and anti-symmetric admittances, an analytical expression for the limiting frequency of plate theories is derived. These two simple analytical expressions for computing the limit of thin and thick plate theories can be useful to choose the appropriate model in each case. Deviations of the TL predictions obtained from different models are observed above these two limiting frequencies. It is also shown that, although the limiting expressions are derived from infinite layer theories, they can be applied to finite sized layers as well. Due to the omission of shear effects in thin plate theories, the refined coincidence and critical frequencies are derived from thick plate theories. Finally, it is observed that plate theories quickly fail for materials that are too soft in terms of longitudinal compression.

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Appendix A. The transfer matrix of an elastic isotropic solid

The transfer matrix of an elastic isotropic layer (defined by the equation $V^{ES}(M) = [T^{ES}]_{4\times4}V^{ES}(M')$ where $V^{ES} = \{u, v, \sigma_{zz}, \sigma_{xz}\}^T$) based on elasticity theory can be written as follows:

$$[T^{ES}]_{4\times4} = \frac{1}{D_1 + D_2 k_t} [T^{ES}_{pq}]$$

where $p, q = 1$ to $4$.

The matrix elements $T^{ES}_{pq}$ are,

- $T_{11} = T_{44} = D_1 \cos(hk_{sz}) + D_2 k_t \cos(hk_{lz})$,
- $T_{22} = T_{33} = D_1 \cos(hk_{lz}) + D_2 k_t \cos(hk_{sz})$,
- $T_{12} = T_{34} = -j[D_2 k_t k_{sz} \sin(hk_{sz}) - D_1 k_t \sin(hk_{lz})] / k_{lz}$,
- $T_{21} = T_{43} = j[D_2 k_t k_{lz} \sin(hk_{lz}) - D_1 k_t \sin(hk_{sz})] / k_{sz}$,
- $T_{13} = T_{24} = \omega k_t [\cos(hk_{sz}) - \cos(hk_{lz})]$,
- $T_{31} = T_{42} = \left(\frac{D_1 D_2}{\omega^2 k_t}\right) T_{13}$,
- $T_{14} = -j\omega [k_{lz} k_{sz} \sin(hk_{sz}) + k_t^2 \sin(hk_{lz})] / k_{lz}$,
- $T_{23} = -j\omega [k_{lz} k_{sz} \sin(hk_{lz}) + k_t^2 \sin(hk_{sz})] / k_{sz}$,
- $T_{32} = -j[D_2 k_t k_{sz} \sin(hk_{sz}) - D_2^2 \sin(hk_{lz})] / (\omega k_{lz})$,
- $T_{41} = -j[D_2 k_t k_{sz} \sin(hk_{sz}) - D_2^2 \sin(hk_{lz})] / (\omega k_{sz})$,

where $D_1 = \mu(k_{sz}^2 - k_t^2)$ and $D_2 = 2\mu k_t$. 

28
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